

# DIFFERENTIATION

## NUMERICAL DIFFERENTIATION

- When we have to differentiate a function given by a set of tabulated values or when a complicated function is involved, numerical differentiation is used.
- The principle behind numerical differentiation is "we find a suitable interpolation polynomial passing through the given data points and then the polynomial is differentiated analytically as required".

## DERIVATIVES FOR EQUALLY SPACED DATA

- Newton Forward Differentiation

Let  $(x_i, y_i)$ ,  $i = 0, 1, 2, \dots, n$  be the given data points and  $x_i = x_0 + ih$ . Assume  $p = \frac{x - x_0}{h}$ .

Then Newton forward interpolation formula is:

$$y_x = y_0 + p\Delta y_0 + \frac{p(p-1)}{2!}\Delta^2 y_0 + \frac{p(p-1)(p-2)}{3!}\Delta^3 y_0 + \dots$$

Differentiating this polynomial, we get

## Newton's Forward Differentiation Formulae

$$\frac{dy}{dx} = \frac{1}{h} \left[ D_0 + \frac{2p-1}{2} D_1 + \frac{3p^2-6p+2}{6} D_2 + \frac{4p^3-18p^2+22p-6}{24} D_3 + \frac{5p^4-40p^3+105p^2-100p+24}{120} D_4 + \dots \right]$$

$$\frac{d^2y}{dx^2} = \frac{1}{h^2} \left[ \frac{6}{2} D_1 + (p-1)D_2 + \frac{6p^2-18p+11}{12} D_3 + \frac{2p^3-12p^2+21p-10}{12} D_4 + \dots \right]$$

## Differentiating

In particular at  $x = x_0$ , we have  $p = 0$ .

Then we have

$$\left. \frac{dy}{dx} \right|_{x_0} = \frac{1}{h} \left[ \frac{6}{2} D_1 - \frac{1}{2} D_2 + \frac{1}{3} D_3 - \frac{1}{4} D_4 + \frac{1}{5} D_5 - \dots \right]$$

$$\left. \frac{d^2y}{dx^2} \right|_{x_0} = \frac{1}{h^2} \left[ \frac{6}{2} D_1 - D_2 + \frac{11}{12} D_3 - \frac{5}{6} D_4 + \dots \right]$$

## Newton's Backward Differentiation Formulae

$$\frac{dy}{dx} = \frac{1}{h} \left[ \frac{6}{2} \tilde{D}_1 + \frac{(2p+1)}{2} \tilde{N}^2 y_n + \frac{(3p^2+6p+2)}{6} \tilde{N}^3 y_n + \frac{(4p^3+18p^2+22p+6)}{6} \tilde{N}^4 y_n + \dots \right]$$

$$\frac{d^2y}{dx^2} = \frac{1}{h^2} \left[ \frac{6}{2} \tilde{N}^2 y_n + (p+1) \tilde{N}^3 y_n + \frac{6p^2+18p+11}{12} \tilde{N}^4 y_n + \dots \right]$$

## Particular case

In particular, when  $x = x_0$ , we get  $p = 0$ .

$$\left. \frac{dy}{dx} \right|_{x_n} = \frac{1}{h} \left[ \frac{6}{5} \tilde{N} y_n + \frac{1}{2} \tilde{N}^2 y_n + \frac{1}{3} \tilde{N}^3 y_n + \dots \right] \dot{u}$$

$$\left. \frac{d^2y}{dx^2} \right|_{x_n} = \frac{1}{h^2} \left[ \frac{6}{5} \tilde{N}^2 y_n + \tilde{N}^3 y_n + \frac{11}{12} \tilde{N}^4 y_n + \frac{5}{6} \tilde{N}^5 y_n + \dots \right] \dot{u}$$

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## Example

Find the first two derivatives at  $x = 1.1$  from the following data:

x:	1	1.2	1.4	1.6	1.8	2.0
y:	0.0000	0.1280	0.5440	1.2960	2.4320	4.0000

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## Solution

The difference table is:

x	y	$\Delta y$	$\Delta^2 y$	$\Delta^3 y$	$\Delta^4 y$
1	0.0				
		0.1280			
1.2	0.1280		0.2880		
		0.4160		0.0480	
1.4	0.5440		0.3360		0
		0.7520		0.0480	
1.6	1.2960		0.3840		0
		1.1360		0.0480	
1.8	2.4320		0.4320		
		1.5680			
2.0	4.0000				

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$$p = \frac{x - x_0}{h} = 0.5 \text{ and } h = 0.2$$

Applying Newton's forward differentiation formula

$$\left. \frac{dy}{dx} \right|_{1.1} = 0.630$$

$$\left. \frac{d^2y}{dx^2} \right|_{1.1} = 6.60$$

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## Example

The following table gives the displacement in metres at different times. Find the velocities and accelerations at  $t = 1.8$  s.

t:	0	0.5	1.0	1.5	2.0
s:	0	8.75	30.00	71.25	140.00

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## Solution

$$h = 0.5,$$

$$p = \frac{t - t_n}{h} = -0.4$$

The difference table is:

t	s	$\nabla s$	$\nabla^2 s$	$\nabla^3 s$	$\nabla^4 s$
0	0				
		8.75			
0.5	8.75		12.50		
		21.25		7.50	
1.0	30.00		20.00		0
		41.25		7.50	
1.5	71.25		27.50		
		68.75			
2.0	140.00				

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Applying Newton's backward differentiation formula

$$\left. \frac{ds}{dt} \right|_{x=1.8} = 143.2$$

$$\left. \frac{d^2s}{dt^2} \right|_{x=1.8} = 128$$

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## UNEQUAL INTERVALS

For unequally spaced data, Lagrange's interpolation formula may be differentiated.

### Example

Find the first derivative at  $x = 2$  for the function given by the data

x	1	1.5	2.0	3.0
y	0	0.4057	0.69315	1.09861

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## Solution

Lagrange interpolation polynomial is:

$$y_x = \frac{(x-1.5)(x-2)(x-3)}{(1-1.5)(1-2)(1-3)} \times 0 + \frac{(x-1)(x-2)(x-3)}{(1.5-1)(1.5-2)(1.5-3)} \times 0.4057$$

$$+ \frac{(x-1)(x-1.5)(x-3)}{(2-1)(2-1.5)(2-3)} \times 0.69315$$

$$+ \frac{(x-1)(x-1.5)(x-2)}{(3-1)(3-1.5)(3-2)} \times 1.09861$$

Differentiating and substituting for  $x$  as 2.

$$\left. \frac{dy}{dx} \right|_{x=2} = 0.48815$$

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## NUMERICAL INTEGRATION

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## PRELIMINARIES

We use numerical integration when the function  $f(x)$  may not be integrable in closed form or even in case of closed form integrable functions the integrand may be complicated or the function is known only at a finite number of points.

### Basic Idea

The function  $f(x)$  is being approximated by a polynomial using interpolation which can be easily integrated.

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## Numerical Integration

Geometrically  $\int_a^b f(x) dx$  represents the area formed by

the curve  $y = f(x)$  and  $x$  - axis between the ordinates  $x = a$  and  $x = b$ .

Let the interval  $[a, b]$  be subdivided into sub intervals each of length  $h$ .

Then  $x_i = x_0 + ih, i = 1, 2, \dots, n$ ,

$$x_0 = a \text{ and } h = \frac{b-a}{n}$$

Let  $y_i = f(x_i), i = 1, 2, \dots, n$ .

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## NEWTON-COTES GENERAL INTEGRATION FORMULA

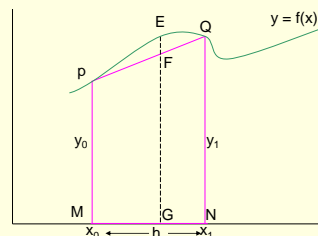
Integrating the Newton forward interpolation polynomial of degree  $\leq n$ , we get

$$\int_a^b f(x) dx = h \left[ \frac{y_0}{1} + \frac{n-1}{2} D_1 y_0 + \frac{(n-1)(n-2)}{6} D_2 y_0 + \frac{(n-1)(n-2)(n-3)}{24} D_3 y_0 + \frac{(n-1)(n-2)(n-3)(n-4)}{120} D_4 y_0 + \dots \right]$$

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## Special Case - I

For  $n = 1$ : Trapezoidal Rule



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## General Form of Trapezoidal rule

$$\int_{x_0}^{x_n} f(x) dx = \frac{h}{2} [y_0 + y_n + 2(y_1 + y_2 + \dots + y_{n-1})]$$

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## Special Case - II

For  $n = 2$ : Simpson's 1/3 Rule

Assume  $n$  to be an even integer.

$$\int_{x_0}^{x_n} f(x) dx = \frac{h}{3} [(y_0 + y_n) + 4(y_1 + y_3 + \dots + y_{n-1}) + 2(y_2 + y_4 + \dots + y_{n-2})]$$

$$= \frac{h}{3} [(\text{sum of end ordinates}) + 4(\text{sum of odd ordinates}) + 2(\text{sum of even ordinates})]$$

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## Special Case - III

For  $n = 3$ : Simpson's 3/8<sup>th</sup> Rule

Assume  $n$  to be a multiple of 3.

$$\int_{x_0}^{x_n} f(x) dx = \frac{3h}{8} [(y_0 + y_n) + 3(y_1 + y_2 + y_4 + y_5 + \dots + y_{n-2} + y_{n-1}) + 2(y_3 + y_6 + \dots + y_{n-3})]$$

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## Example

Evaluate  $\int_1^2 \frac{1}{x} dx$  using

- Trapezoidal rule
  - Simpson's rule and
  - Simpson's rule and compare the values.
- Divide the range into 6 sub intervals.

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## Solution

x	f(x)
1	1
$\frac{7}{6}$	0.8571
$\frac{8}{6}$	0.7500
$\frac{9}{6}$	0.6667
$\frac{10}{6}$	0.6000
$\frac{11}{6}$	0.5455
2	0.5000

**Trapezoidal rule**

$$\int_{x_0}^{x_2} f(x) dx = 0.6949$$

**Simpsons 1/3<sup>rd</sup> rule**

$$\int_{x_0}^{x_2} f(x) dx = 0.6932$$

**Simpsons 3/8<sup>th</sup> rule**

$$\int_{x_0}^{x_2} f(x) dx = 0.6932$$

**Exact Value = 0.6931**

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## GAUSSIAN QUADRATURE

In Gaussian quadrature sampling points and the weights have been optimized. In Newton-Cotes formulae we choose  $(n+1)$  equally spaced points  $x_i$  in the interval of integration. These formulae gives exact values if the integrand is a polynomial of degree  $< n$ .

Gauss showed that by choosing the  $(n+1)$  points suitably, the formula can be made exact when the integrand is a polynomial of degree  $< (2n+1)$ .

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Using the linear transformation,

$$x = \frac{b-a}{2} t + \frac{a+b}{2}$$

the integral  $\int_a^b F(x) dx$  can be transformed into

$$\int_{-1}^1 f(t) dt.$$

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## GAUSSIAN QUADRATURE FORMULA

**One Point**

$$\int_{-1}^1 f(t) dt = 2 f(0)$$

**Two Points**

$$\int_{-1}^1 f(x) dx = f\left(-\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}\right)$$

**Three Points**

$$\int_{-1}^1 f(t) dt = \frac{8}{9} f(0) + \frac{5}{9} \left[ f\left(-\sqrt{\frac{3}{5}}\right) + f\left(\sqrt{\frac{3}{5}}\right) \right]$$

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## Example

Evaluate  $\int_0^1 \frac{dx}{1+x}$  by Gaussian quadrature

formula with one point, two points and three points.

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## Solution

Put  $x = \frac{t+1}{2}$ ,  $dx = \frac{1}{2} dt$

One point: 0.6667

Two points: 0.6923

Three points: 0.693122

Exact value: 0.693147

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